

Electric three-finger robotic gripper

Get A Soft Grip!



Features

1. Precise control:

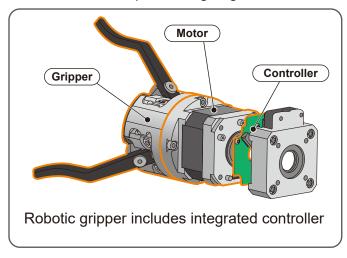
Position and speed adjustments can be made in increments of 0.1%, and gripping force adjustments in increments of 0.5%. Additional functions include 2 stage operation and grip detection.

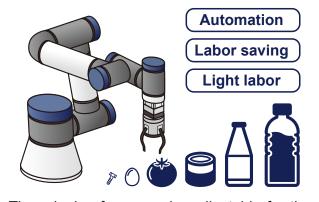
2. Hollow channel structure:

Tubes and cables can be passed through the hollow channel structure which makes it possible the use of additional equipment such as cameras, sensors and pneumatic tools.

3. Customization:

The fingers can be easily replaced and their shapes can be customized. Mounting surfaces allow the use of an optional finger, guide and other equipment.





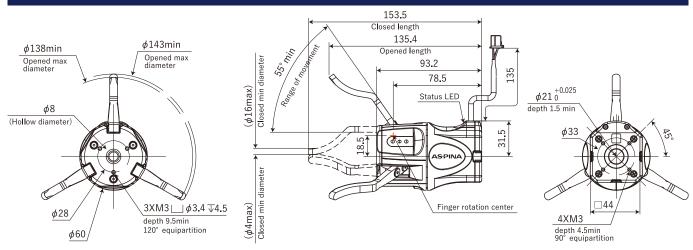
The gripping force can be adjustable for the softness or hardness material.

Specifications

Maximum opened diameter	Ф143mm			
Gripping force *1	5N			
Maximum workpiece weight *2	50g			
Maximum workpiece weight *3	300g			
	0.25 ~ 10sec			
Opening and closing speed				
Maximum finger length	100mm			
Positioning repeatability	±50 um (no load)			
Weight	640g			
Dimensions	Ф60 × 155 mm			
Lifetime	10 million cycles (no load)			
Input voltage	24V±10%			
Maximum current (rated operation)	0.6A Max peak			
Digital I/F	Selectable 4 digital I/F from 4 inputs and 2 outputs			
Input	●ON/OFF	●Home	Operation	●Stop command etc.
Output	●ON/OFF	 Ready/Busy 	●Alarm	 Gripping range error signal, etc.
Serial I/F	RS - 485 (Modbus RTU)			
Indicator	Status LED (Green / Red / Orange)			
Protective function	Voltage Temperature Parameter setting error etc.			
Operating ambient temperature	0 ~ +40°C			
Storage temperature	-10 ~ +50°C			
Robots connectivity				
Plug & Play / Mounting attachment	Universal robots, Techman robot, FANUC			

^{*1.} Measuring with one finger at 30 mm *2. At 70 mm distance from the finger rotation center. *3. At 30 mm distance from the finger rotation centerline drawing

Outline



□ Contents

- Robotic gripper Cable (3 m)
- Standard finger (Installed into robotic gripper)
- Finger fixing screw (Installed into robotic gripper)
- Non-slip tube for standard finger (For trial use)

\square **Options** (Please contact us for details about optional items.)

Attachment and/or cable for robots from most major robot manufacturers

■ Contact

■ Manufacturer ASPINA

Shinano Kenshi Co., Ltd. 1078, Kami-maruko, Ueda City, Nagano 386-0498 Japan Jp.aspina-group.com ISO 9001:2015 / ISO 14001:2015 accreditation